



Use of AI in dairy farming and research

Mutian Niu
SVT Conference 2025



Artificial Intelligence 4 Animal Science

[Home](#) [Programme](#) [Abstract submission](#) [Venue](#) [Accomodations](#) [Contacts](#) [Registration](#)



ai4as.eaap.org

EAAP conference: Zurich, 4-6 June 2025

What is artificial intelligence (AI)?

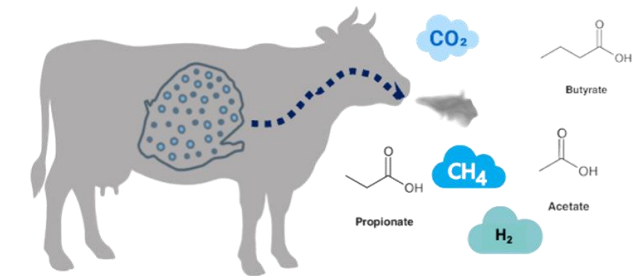
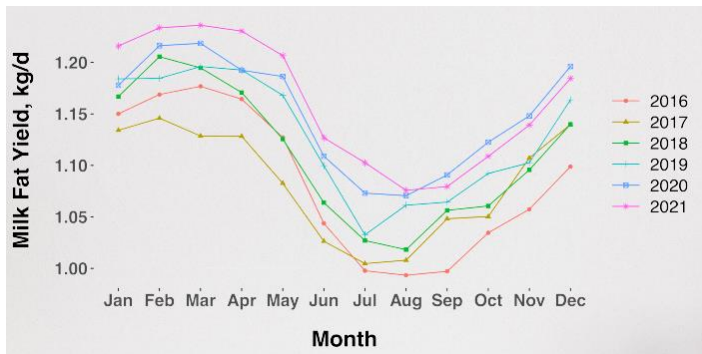
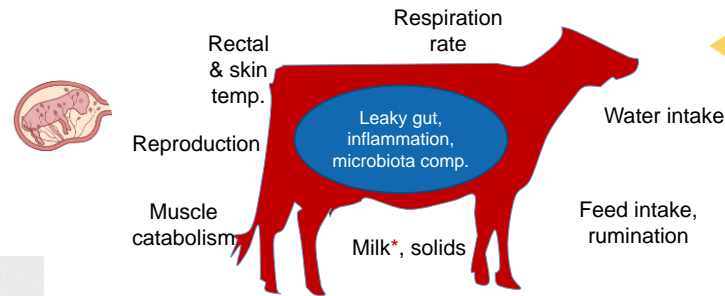
- Ability of machines or computer systems to perform tasks that typically require human intelligence, or, **the capability of machines to mimic human intelligence.**
 - Learning
 - Problem-solving
 - Decision-making
 - Pattern recognition
 - Robotics
 - Smart feeding stations
 - ...

- AI research cases
- Key components for the use of AI in dairy farming

Interdisciplinary research at ETH Animal Nutrition group to improve animal welfare

Livestock

Environment



Optimizing nutrition to counteract the impact of heat stress

Better monitoring and assessment on animal behavior and welfare

Non-invasive exhalomics and breathomics approaches to reveal nutritional physiology and health

Case #1: Prediction of respiratory rate

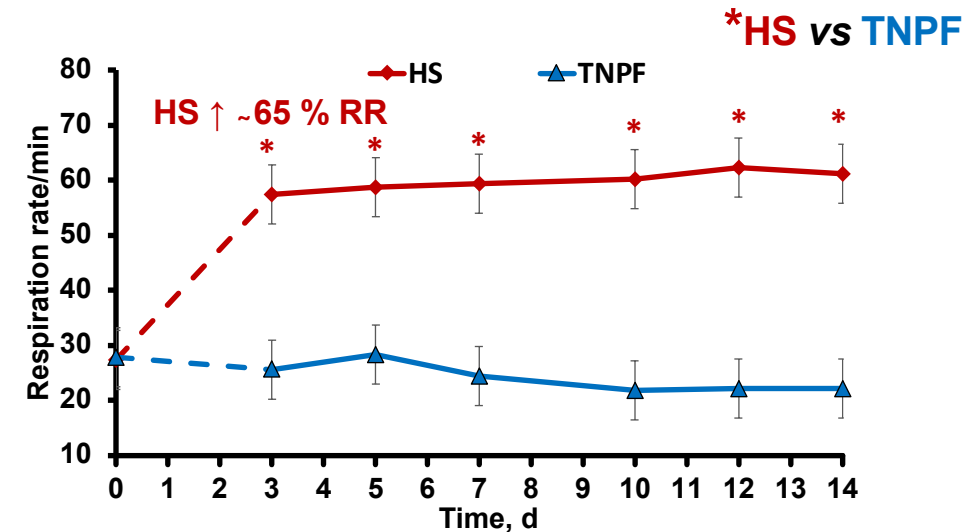
The importance of respiratory rate (RR) in health and welfare

Respiratory diseases

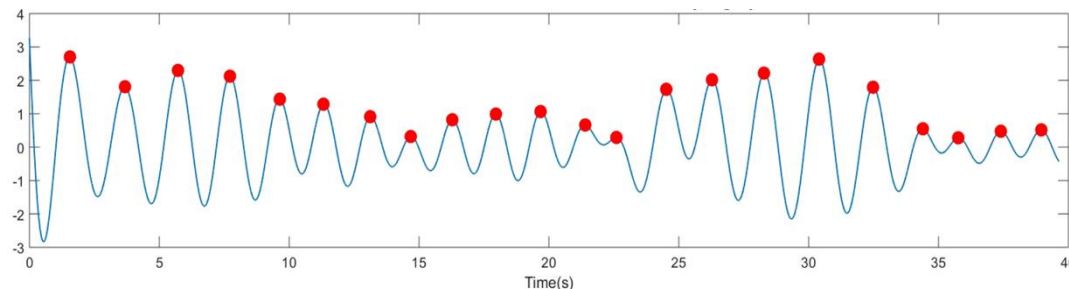
- Mainly affect young animals
- Reduce growth, risk of mortality

Heat stress

- Change of animal behavior
- Reduce feed intake and milk production, increase water intake...



Measurement of RR



Traditional approaches RR measurement



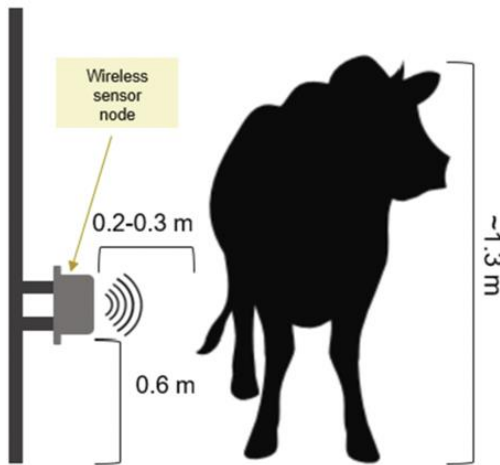
Labor-intensive

Not applicable to large number of animals



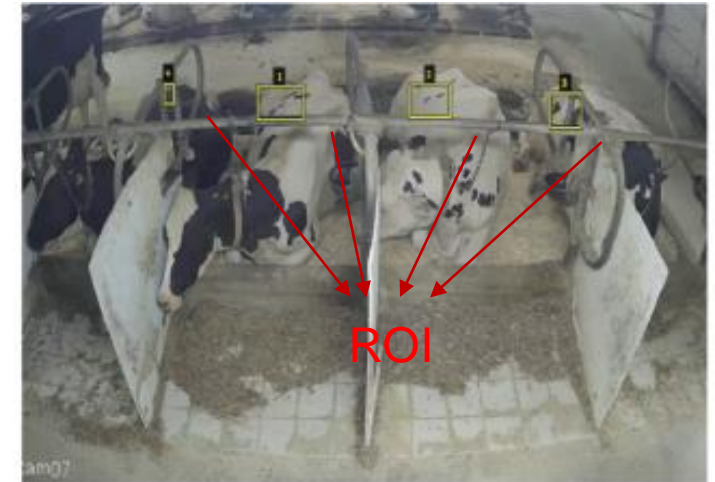
Other approaches?

Recent developed alternative methods to measure RR



Radar-based system

Signal of interest can be disturbed



Camera-based system

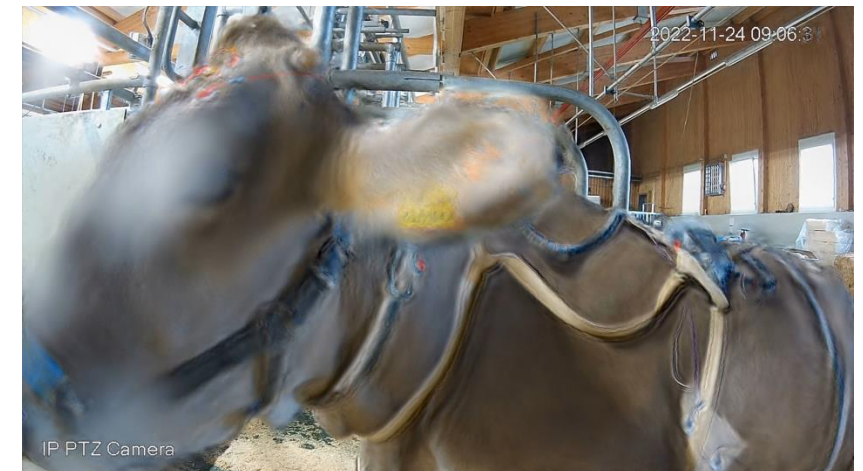
Manual selection of short videos of the Region of Interest (ROI)

Objective: to develop an end-to-end model to predict RR of cows using RGB videos without manual selection of ROI.

Respiratory patterns

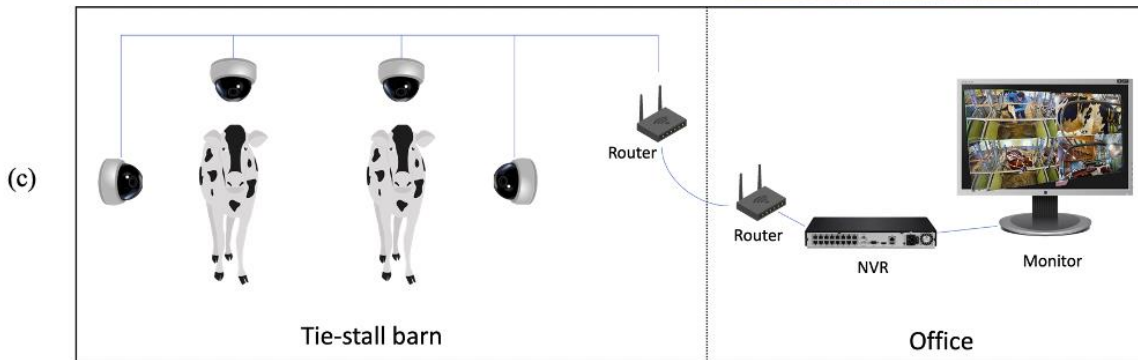
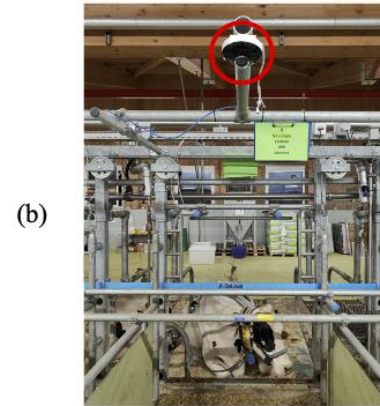


	165	187	209	58	7
14	125	233	201	98	159
253	144	120	251	41	147
67	100	32	241	23	165
209	118	124	27	59	201
210	236	105	169	19	219
35	178	199	197	4	14
115	104	34	111	19	196
32	69	231	203	74	



- Respiratory patterns are visible in RGB videos.

Experiment: data collection in the tie-stall barn



Gold standard: Embla
XactTrace Respiration Belt



- Video recording: 2 RGB cameras for each cow, 6 cows, 24 hours

Data selection



(a)



(b)



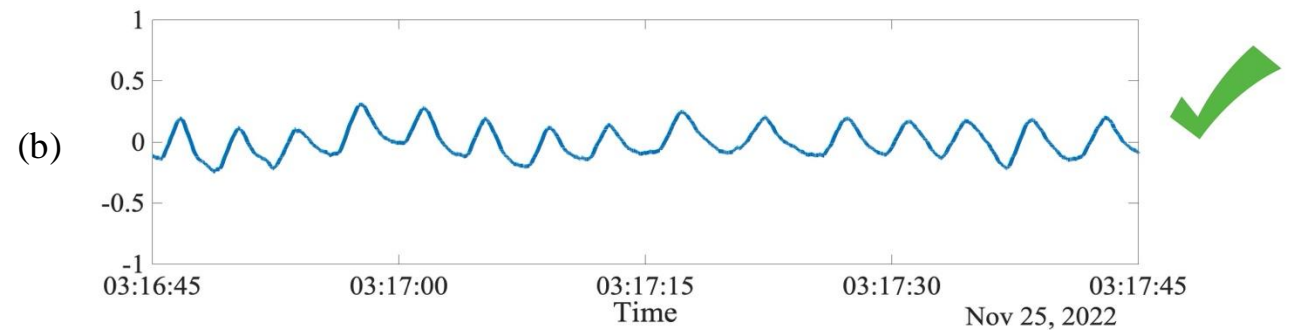
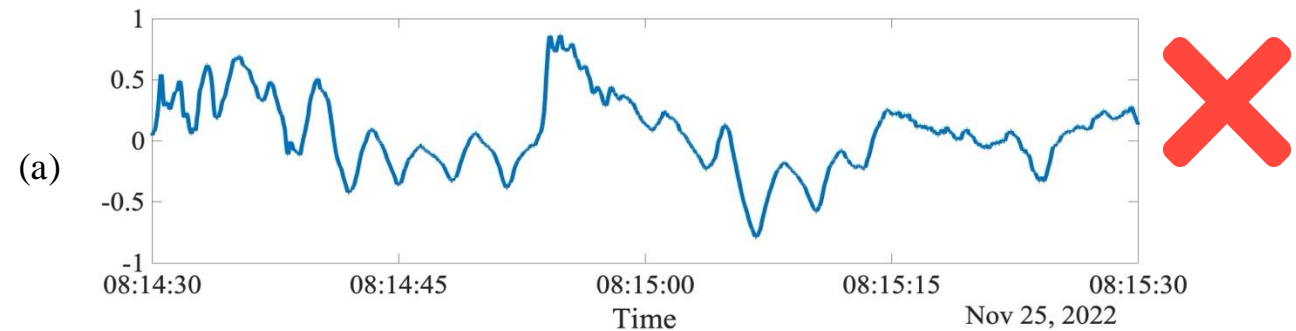
(c)



(d)

Video selected from top and side views, day and night

Video selection: 18 videos (18 min 11s ± 13 min 44s)



Gold standard when the cow is:
(a) significantly moving; (b) the cow is resting

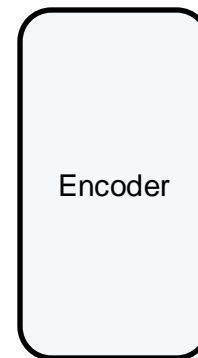
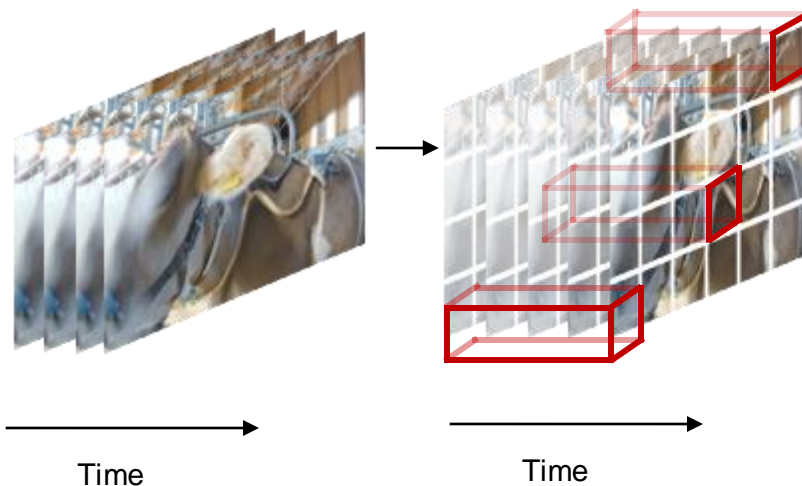
The cow is in resting status with minimal movement

Development of the end-to-end method

Training: data from 4 cows

Validation: data from 1 cow

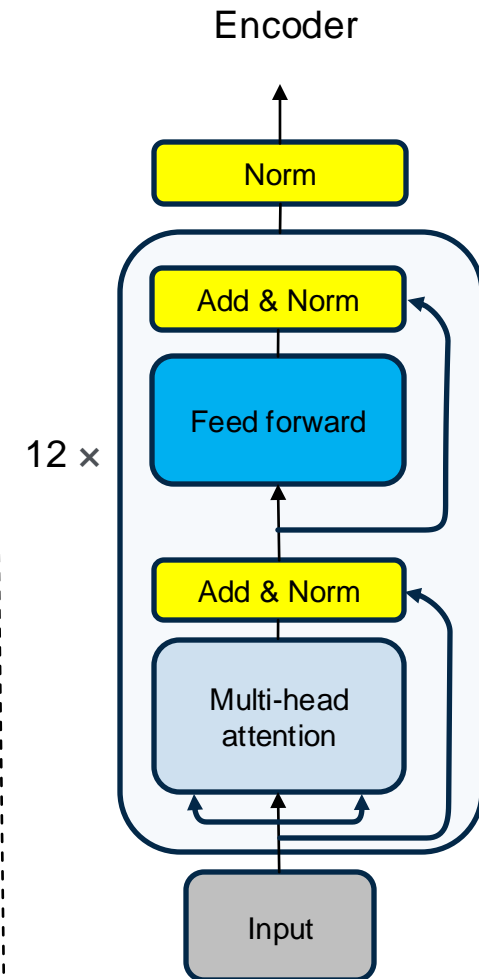
Test: data from 1 cow



RR

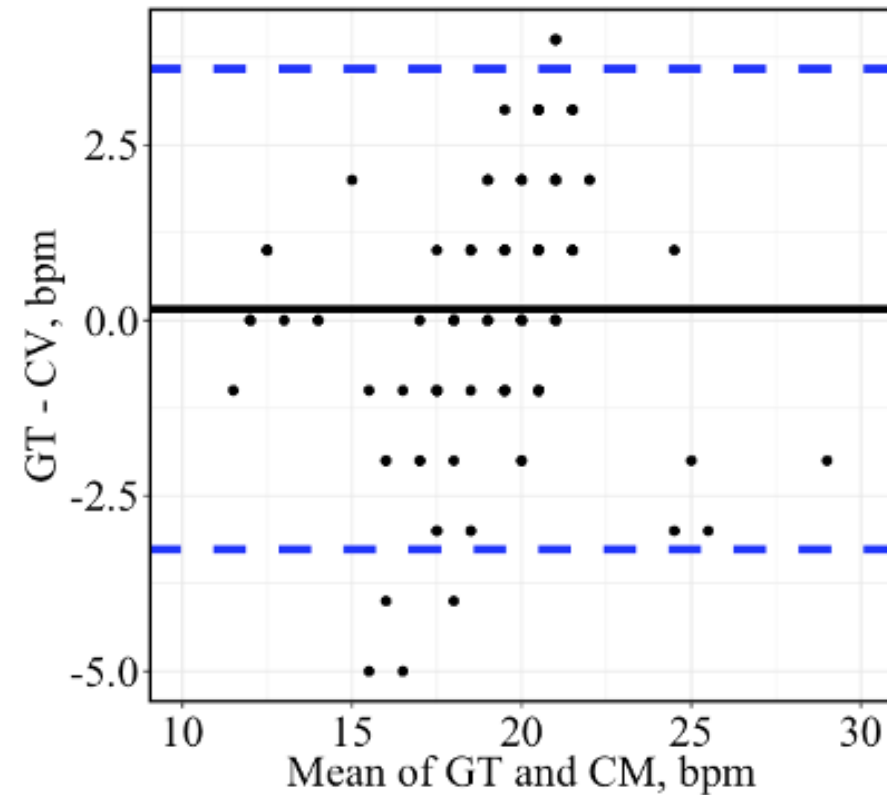
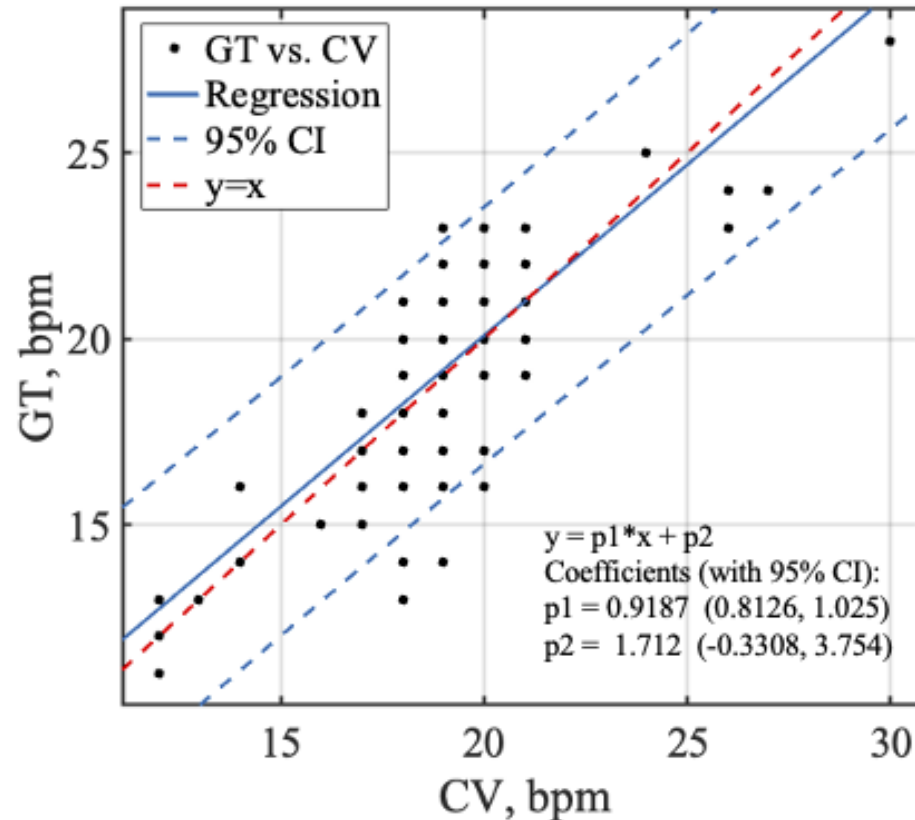
23
22
20
...

Transformer model: VideoMAE



(Tong et al., 2022; Wang et al., 2024)

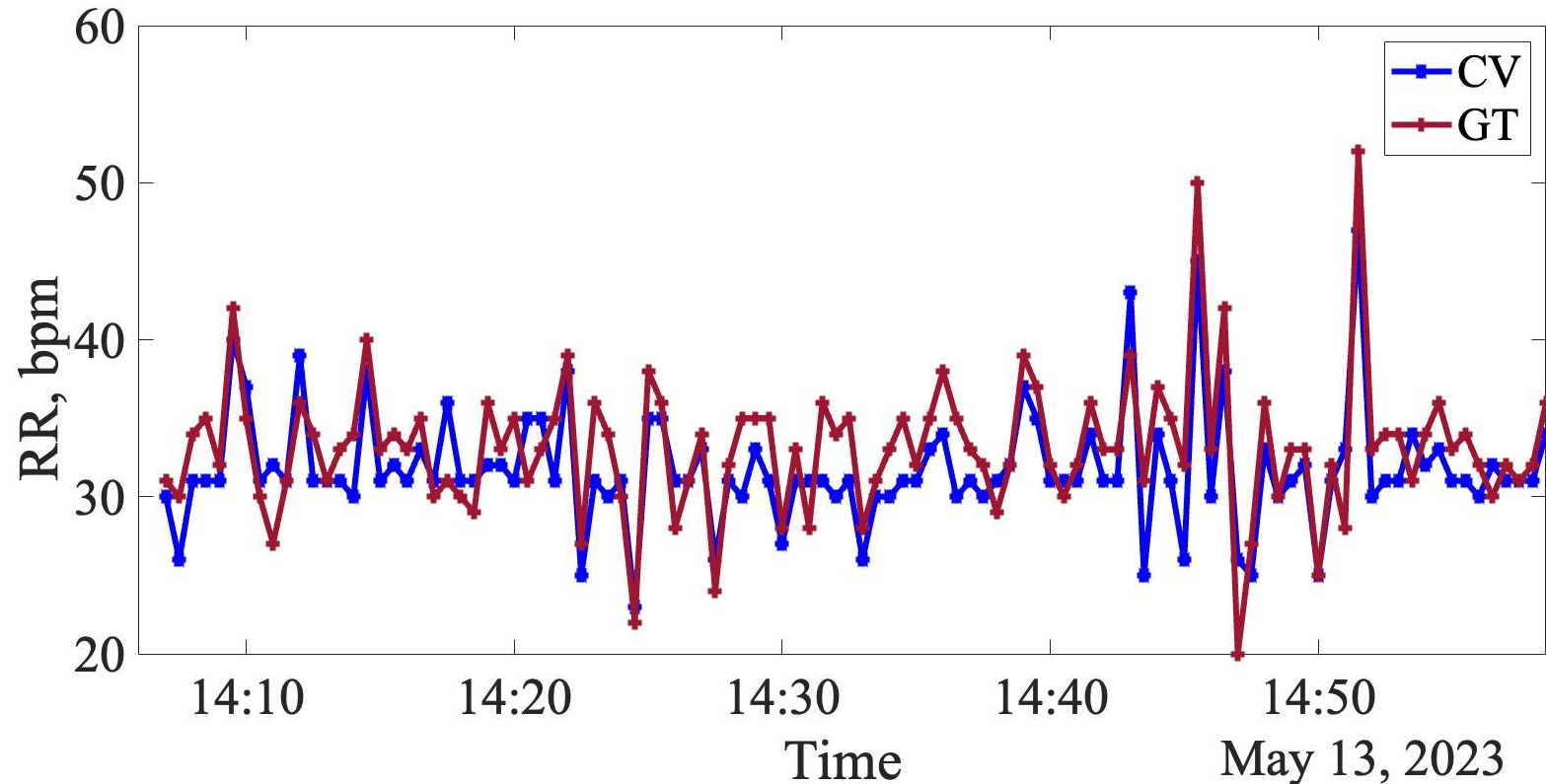
Results – on test set



Mean absolute error (MAE): 2.58 breaths/minute (bmp)
Root mean square error (RMSE): 3.52 bpm

Root mean squared prediction error: 15.03%
Pearson correlation: 0.86

Results – on a long video



Mean absolute error (MAE): 2.49 breaths/minute (bmp)
Root mean square error (RMSE): 2.91 bpm

Root mean squared prediction error: 8.78%
Pearson correlation: 0.74

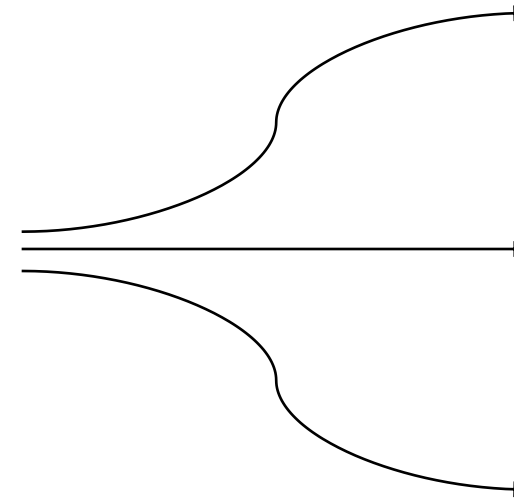
Case #2: Continuous tracking of dairy cows

Video-based tracking – A prerequisite for further applications?



- **Identification** at time t
- **Position** at time t
- **Trajectory** during Δt

Also called: **Multiple Object Tracking (MOT)**



Behavioural analyses

Early detection of health problems

Early detection of management problems

Knowledge gaps and objectives in objective tracking

Knowledge gaps

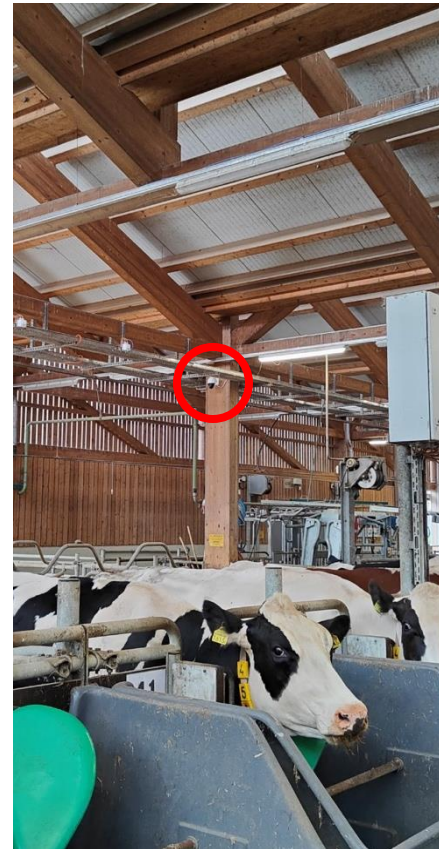
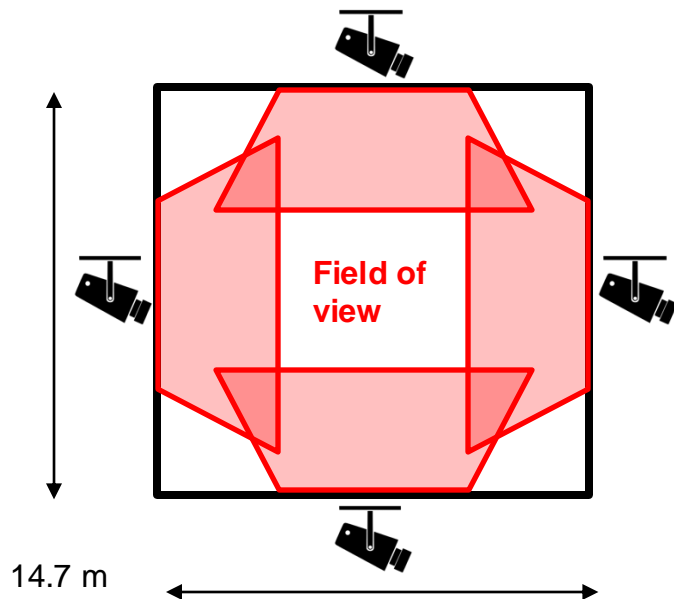
- **Reappearing** animals are subject to misidentification.
- Poor performance on **long videos (≥ 30 minutes)**, **night**?

Objectives

- 1) Provide the correct identification (ID) to **reappearing animals**.
- 2) Evaluate **performance** compared to established tracking algorithms.

Data collection set-up

- **13 dairy cows**
 - 7 Holstein, 6 Red Holstein
- **Continuous recording**
(August – September 2023)
- **4 camera angles**, 15fps, 2560 x 1440



Tracking approach

Object detector

- Goal: Recognise and localise cows in frame
- Model: YOLOv8
- Trained on: **Dataset (1)**



Image classifier

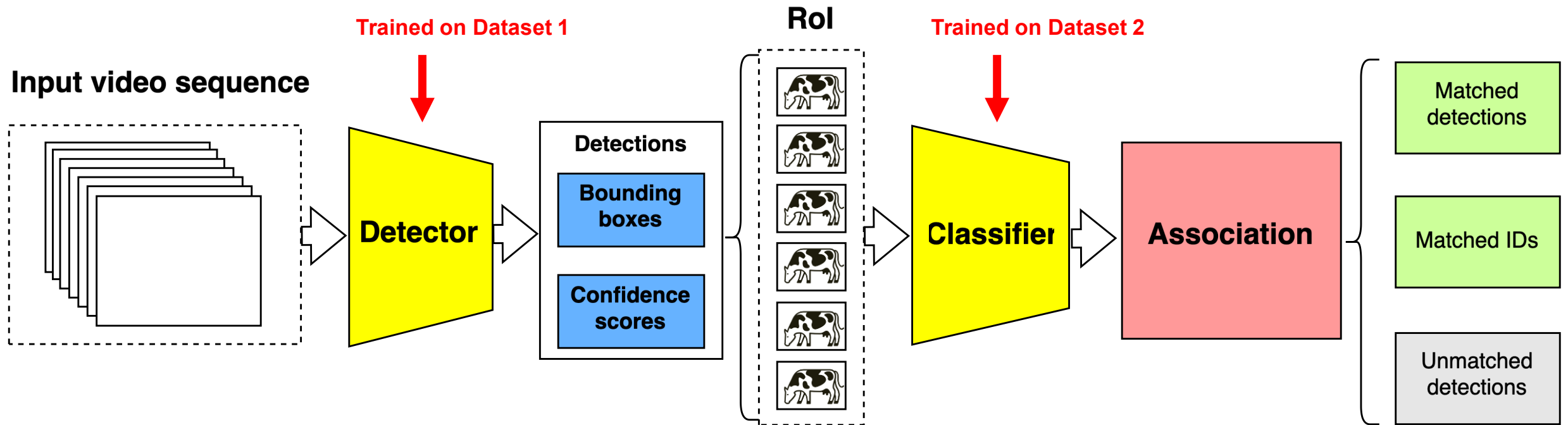
- Goal: Generate classification probabilities
- Model: YOLOv8 Classify
- Trained on: **Dataset (2)**



Association

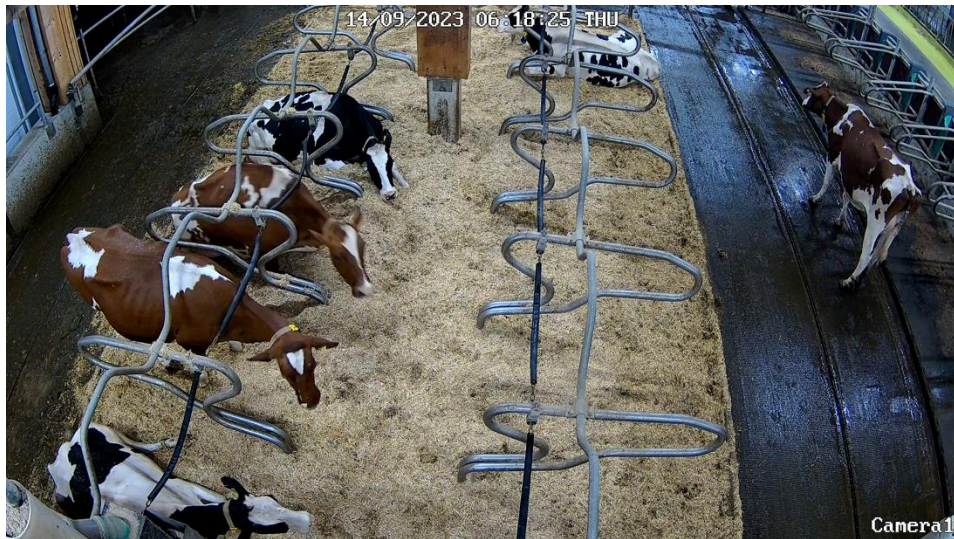
- Two rounds of Hungarian matching with thresholds (Kuhn, 1955)

Tracking approach



Scheme of the proposed model

Input – Output



Datasets for training and testing

Dataset (1): Object detector

	# Frames	# Instances
Training	672	3,830
Validation	333	2,256
Total	1,005	6,086

Dataset (2): Image classifier

	# Instances	# Classes
Training	6,139	13
Validation	1,750	13
Total	7,889	13

Dataset (3): Test videos for tracking

# Video	# Camera	Duration (hh:mm:ss)	Time	# Animals	# Reappearances	Start time
1	1	00:05:00	Day	13	0	17:55:26
2	2	00:05:00	Night	10	4	04:11:36
3	2	00:30:01	Day	11	12	14:48:55
4	1	00:30:00	Night	11	10	20:18:36
5	2	01:00:01	Day	11	29	13:29:37
6	1	01:00:01	Night	13	32	01:19:36

Proposed method performs better in case of reappearances

Method		SORT					DeepSORT			Developed method		
Video	Time	#Animal	#Reap.*	MOTA↑**	IDF1↑	HOTA↑	MOTA↑	IDF1↑	HOTA↑	MOTA↑	IDF1↑	HOTA↑
Test 1	Day	13	0	0.7180	0.8114	0.7972	0.8810	0.8447	0.8747	0.8702	0.9305	0.9158
Test 2	Night	10	4	0.8586	0.9233	0.8924	0.9352	0.9653	0.9632	0.9434	0.9712	0.9686
Test 3	Day	11	12	0.9180	0.8126	0.8349	0.9752	0.7887	0.8463	0.9771	0.9883	0.9828
Test 4	Night	11	10	0.7367	0.7396	0.7533	0.7607	0.7937	0.8103	0.7725	0.8918	0.8701
Test 5	Day	11	29	0.7846	0.7276	0.7161	0.9432	0.6875	0.7425	0.9381	0.9666	0.9421
Test 6	Night	13	32	0.7719	0.5496	0.6164	0.8900	0.5117	0.6293	0.8635	0.9261	0.8925

Bold values are the highest for each video.

* number of reappearances

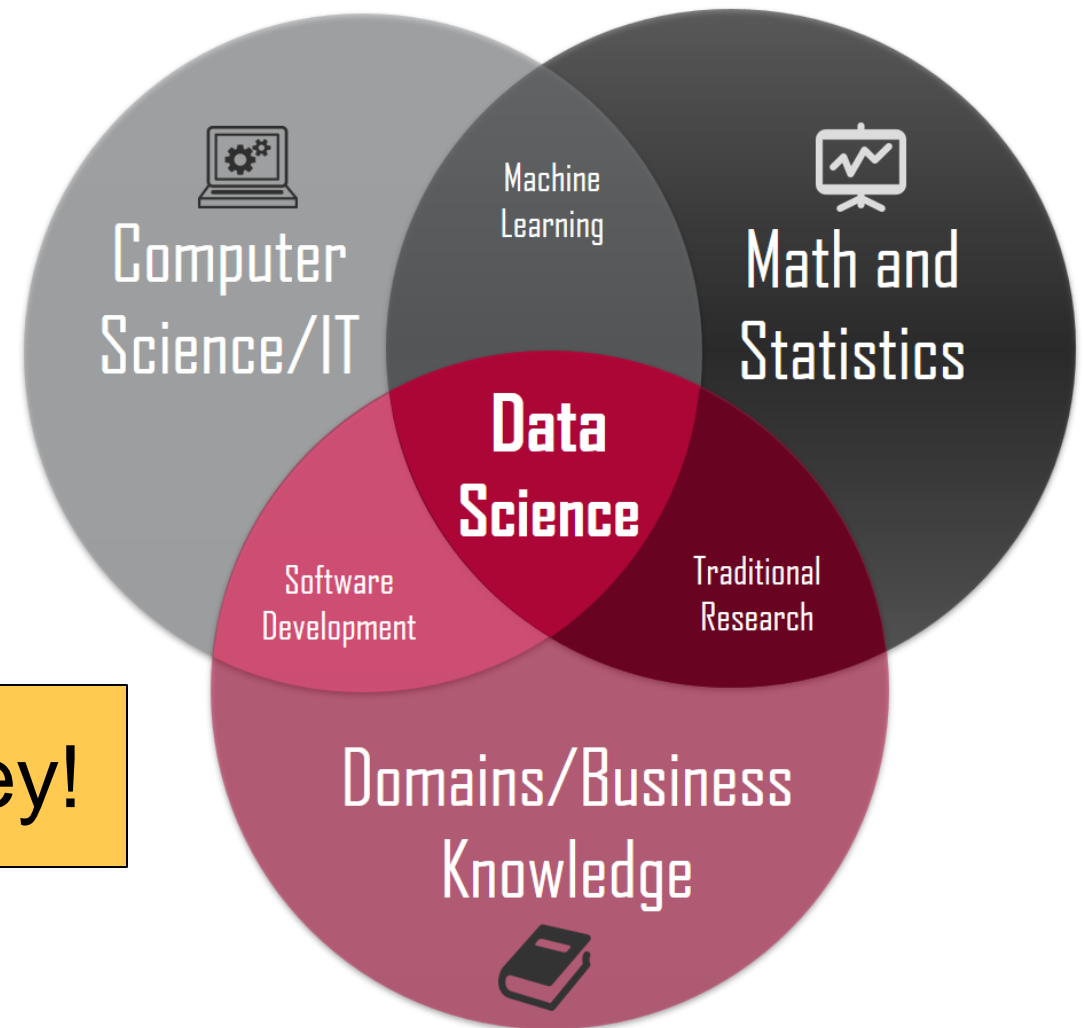
** ↑ means the higher the better

- **MOTA**: Matching at the detection level.
- **IDF1**: Matching at the trajectory level.
- **HOTA**: Balanced indicator for detection and association accuracy.

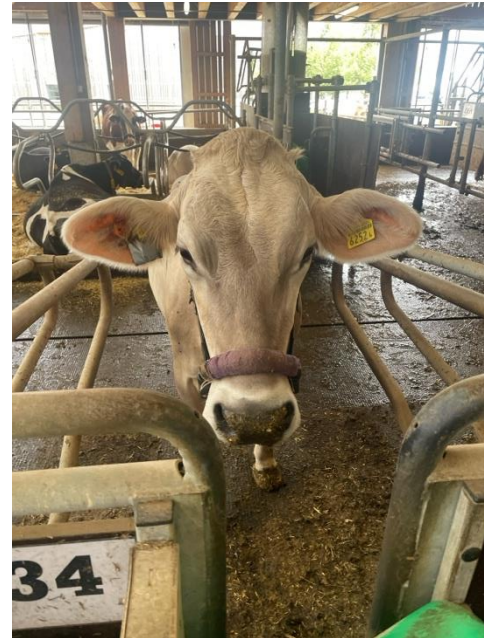
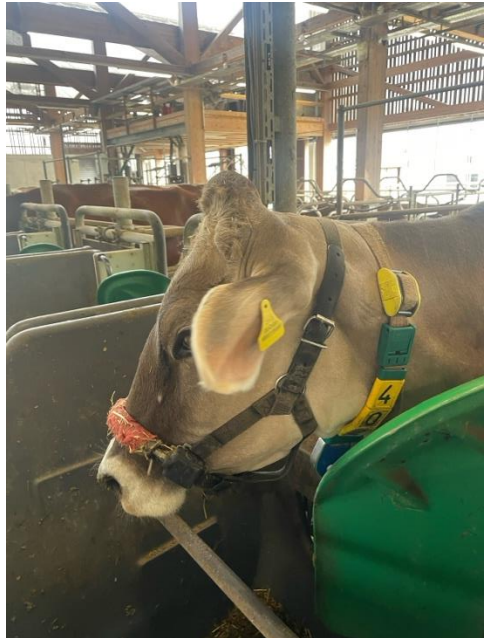
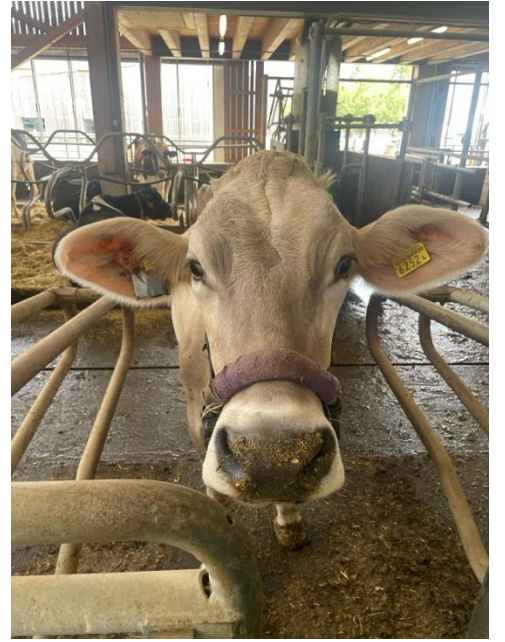
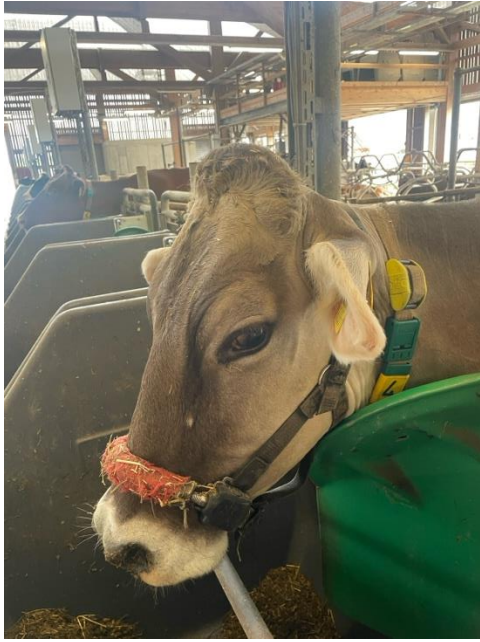
- The developed method showed promising performance, especially on videos with long duration and more times of re-entering the FOV.
- the proposed method showed significant improvements in long videos.

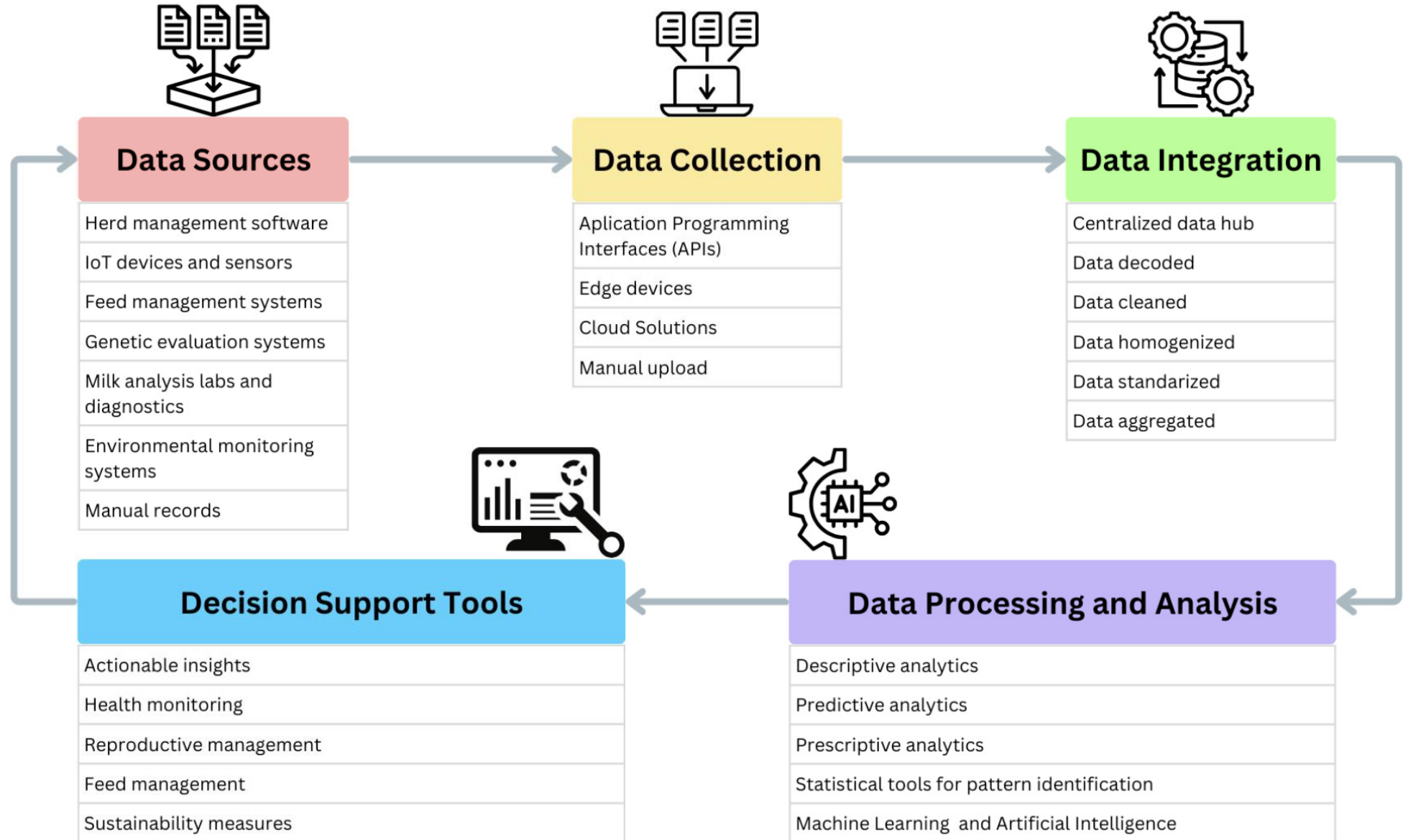
Take home message

- **Having a clear objective!**
- **Final adequate methods to apply!**
- **Have/collect good quality data!**

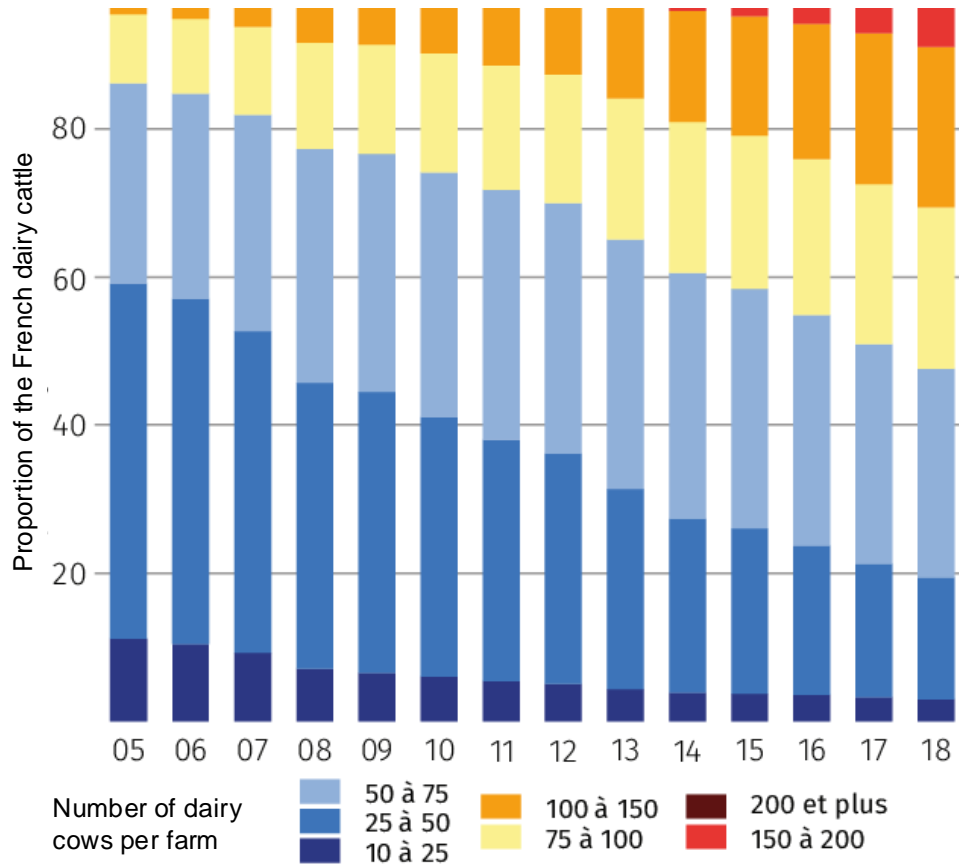


Data and data integration is key!





Ongoing intensification in the dairy sector



Change in the distribution of dairy cows by farm size in France, from 2005 to 2018 (Forget et al. 2019).

Country	2002	2006	2010	2014	2018	Increase since 2010 (%)
Denmark	2.2	8	22.5	24	22	-2
The Netherlands	2	4	11	18	23	109
Germany	~0	0.5	2	6.5	15	650
Norway	~0	1	6.5	13.5	23	254
Sweden	1	5	13	23	30	131
Canada	~0	0.5	2	5	11.5	475

Sources: Barkema et al. (2015), Hansen (2015), Tse et al. (2017), CDIC (2019), and Vik et al. (2019).

Percentage of dairy farms with AMS in selected countries (Eastwood and Renwick, 2020).

Localized AI tools for future dairy farming?

- Learning
- Problem-solving
- Decision-making
- Pattern recognition



Data-Driven Intelligence

- Precision nutrition and feed management
- Disease detection and health monitoring
- Productivity and reproduction optimization
- Sustainability and resource efficiency
- Robotics and intelligent systems



Objective-driven AI applications

Thank you!

mutian.niu@usys.ethz.ch